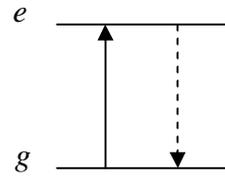
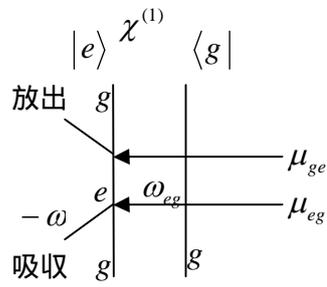


$$\omega_0 = \omega_{eg} = \omega_e - \omega_g = \omega_{21}$$

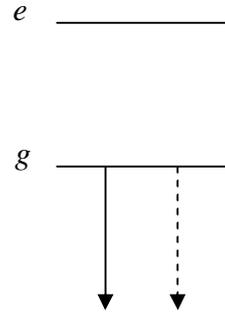
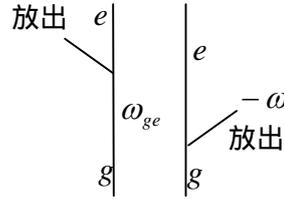
$$\chi^{(1)}(\omega; -\omega) \propto \frac{1}{\omega_0 - \omega - i\gamma_2}$$

共鳴項 $\mu_{ge} \rho_{eg}(+\omega) e^{-i\omega t}$



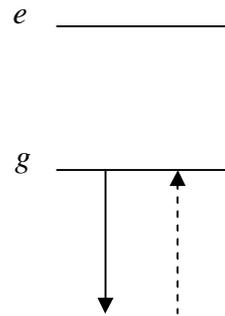
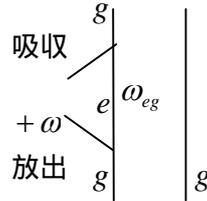
$$\chi^{(1)}(\omega; -\omega) \propto \frac{-1}{-\omega_0 - \omega - i\gamma_2} = \frac{1}{\omega_0 + \omega + i\gamma_2}$$

非共鳴項 $\mu_{eg} \rho_{ge}(+\omega) e^{-i\omega t}$



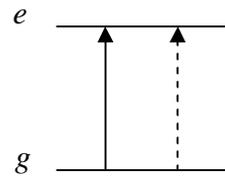
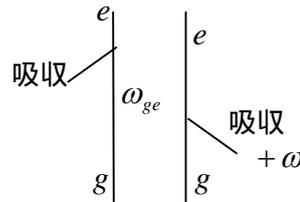
$$\chi^{(1)}(-\omega; \omega) \propto \frac{1}{\omega_0 + \omega - i\gamma_2}$$

非共鳴項 $\mu_{ge} \rho_{eg}(-\omega) e^{i\omega t}$



$$\chi^{(1)}(-\omega; \omega) \propto \frac{-1}{-\omega_0 + \omega - i\gamma_2} = \frac{1}{\omega_0 - \omega + i\gamma_2}$$

共鳴項 $\mu_{eg} \rho_{ge}(-\omega) e^{i\omega t}$



$$P^{(1)}(t) = \varepsilon_0 \frac{E_0}{2} [\chi^{(1)}(\omega) e^{-i\omega t} + \chi^{(1)}(-\omega) e^{i\omega t}] \quad E(t) = \frac{E_0}{2} (e^{-i\omega t} + e^{i\omega t})$$

$$\chi^{(1)}(\omega) = \chi^{(1)}(\omega; -\omega)$$

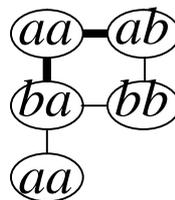
$$= \frac{N |\mu_{12}|^2}{V \varepsilon_0 \hbar} \left(\frac{1}{\omega_0 - \omega - i\gamma_2} + \frac{1}{\omega_0 + \omega + i\gamma_2} \right)$$

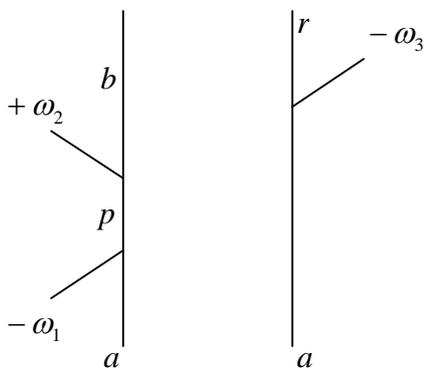
$$\chi^{(1)}(-\omega) = \chi^{(1)}(-\omega; \omega)$$

$$= \frac{N |\mu_{12}|^2}{V \varepsilon_0 \hbar} \left(\frac{1}{\omega_0 + \omega - i\gamma_2} + \frac{1}{\omega_0 - \omega + i\gamma_2} \right)$$

／ 右上がり -ω

＼ 右下がり +ω





arbp 2準位系 gかe

$a = g$

$r, b, p = e, e, e$

g, e, e

反転対称性がない場合

e, g, e

e, e, g

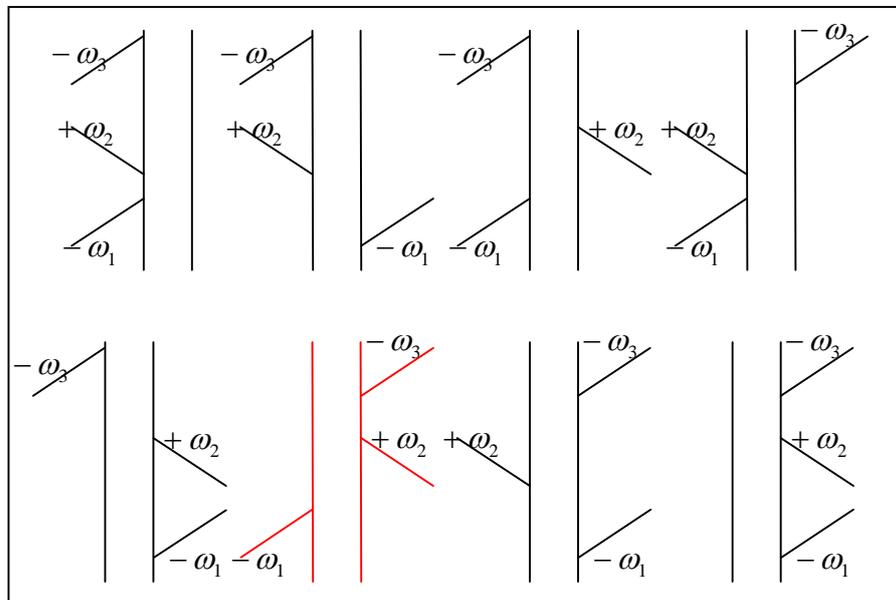
$\mu_{gg}, \mu_{ge}, \mu_{eg}, \mu_{ee} \neq 0$

g, g, e

g, e, g

e, g, g

g, g, g



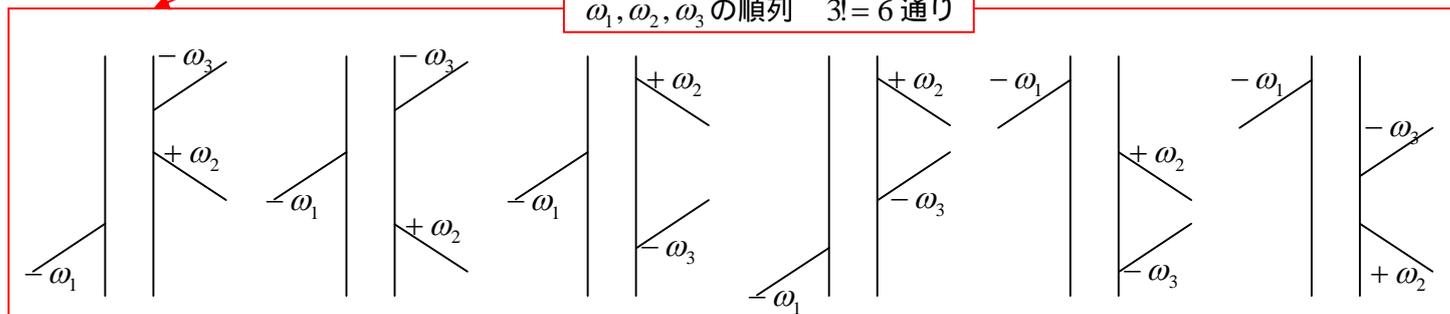
左右どちらに ω_j が

くるか

$2 \times 2 \times 2 = 8$ 通り

計 $8 \times 6 = 48$ 通り

$\omega_1, \omega_2, \omega_3$ の順列 $3! = 6$ 通り



上のダイアグラムに対応する $\chi^{(3)}$

$\chi_{klmn}^{(3)}(\omega_3 - \omega_2 + \omega_1; -\omega_3, \omega_2, -\omega_1)$

$$= \frac{N}{V} \frac{1}{\epsilon_0 \hbar^3} \sum_{arbp} \mu_{ar}^l \mu_{rb}^k \mu_{bp}^m \mu_{pa}^n \frac{-1}{\omega_{br} - (\omega_3 - \omega_2 + \omega_1) - i\gamma_{br}} \frac{1}{\omega_{ba} - (-\omega_2 + \omega_1) - i\gamma_{ba}} \frac{1}{\omega_{pa} - \omega_1 - i\gamma_{pa}} \rho_{aa}^{(0)}$$

$$P_k^{(3)}(\omega_3 - \omega_2 + \omega_1) = \epsilon_0 \chi_{klmn}^{(3)}(\omega_3 - \omega_2 + \omega_1; -\omega_3, \omega_2, -\omega_1) \left(\frac{E_l(\omega_3)}{2} e^{-i\omega_3 t} \right) \left(\frac{E_m(-\omega_2)}{2} e^{i\omega_2 t} \right) \left(\frac{E_n(\omega_1)}{2} e^{-i\omega_1 t} \right)$$

2準位系で反転対称性がある場合

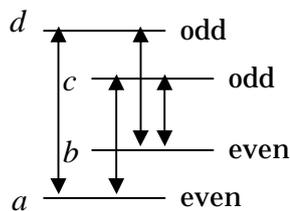
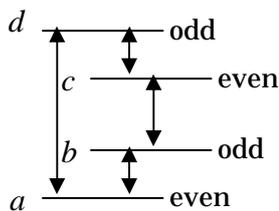
$\mu_{pa}, \mu_{bp}, \mu_{rb}, \mu_{ar} = \mu_{ge}$ or μ_{eg} $a = g$ から出発すれば 3回の遷移は $g \rightarrow e \rightarrow g \rightarrow e$ のみ 1通り

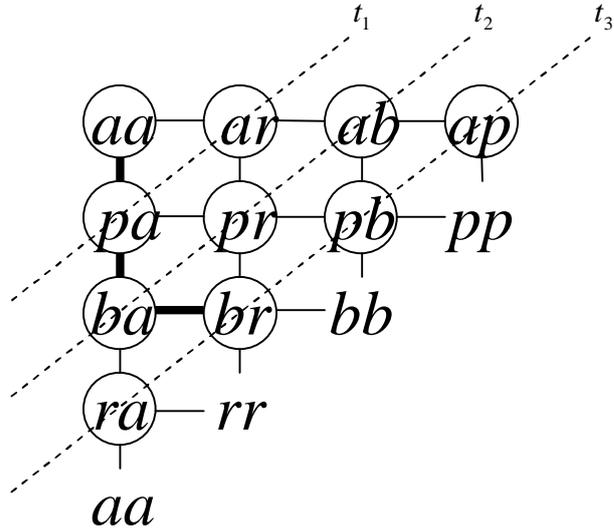
4準位系で反転対称性がある場合

3回の遷移ごとに2つの可能性

$2 \times 2 \times 2 = 8$ 通り

計 $48 \times 8 = 384$ 通り





$$\text{期待値 } P = \frac{N}{V} \text{Tr}(\rho\mu)$$

$$\rho_{br}\mu_{rb} \quad \text{or} \quad \mu_{rb}\rho_{br}$$

$$\begin{aligned} \langle \psi | A | \psi \rangle &= \langle C_1\phi_1 + C_2\phi_2 | A | C_1\phi_1 + C_2\phi_2 \rangle \\ &= C_1^* C_1 A_{11} + C_2^* C_1 A_{21} + C_1^* C_2 A_{12} + C_2^* C_2 A_{22} \\ &= \rho_{11} A_{11} + \rho_{12} A_{21} + \rho_{21} A_{12} + \rho_{22} A_{22} \\ &= \text{Tr}(\rho A) = \text{Tr}(A \rho) \end{aligned}$$

$$\therefore \rho A = \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} = \begin{pmatrix} \rho_{11} A_{11} + \rho_{12} A_{21} & \rho_{11} A_{12} + \rho_{12} A_{22} \\ \rho_{21} A_{11} + \rho_{22} A_{21} & \rho_{21} A_{12} + \rho_{22} A_{22} \end{pmatrix}$$

$$\therefore A \rho = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} = \begin{pmatrix} A_{11} \rho_{11} + A_{12} \rho_{21} & A_{11} \rho_{12} + A_{12} \rho_{22} \\ A_{21} \rho_{11} + A_{22} \rho_{21} & A_{21} \rho_{12} + A_{22} \rho_{22} \end{pmatrix}$$

巨視的分極

$$P(t) = \frac{N}{V} (\rho_{21} \mu_{12} + \rho_{12} \mu_{21}) = \frac{N}{V} (\mu_{12} \rho_{21} + \mu_{21} \rho_{12})$$