

$$Rc - \mathbf{R} \cdot \mathbf{v} = \mathbf{R} \cdot \mathbf{u} \quad \text{with } \mathbf{u} \equiv c\hat{\mathbf{R}} - \mathbf{v}$$

$$\begin{aligned} \mathbf{E}(\mathbf{r}, t) &= \frac{q}{4\pi\epsilon_0} \frac{R}{(\mathbf{R} \cdot \mathbf{u})^3} [(c^2 - v^2)\mathbf{u} + \mathbf{R} \times (\mathbf{u} \times \mathbf{a})] \\ &= \frac{q}{4\pi\epsilon_0} \frac{R}{(\mathbf{R} \cdot \mathbf{u})^3} [(c^2 - v^2)\mathbf{u} + (\mathbf{R} \cdot \mathbf{a})\mathbf{u} - (\mathbf{R} \cdot \mathbf{u})\mathbf{a}] \quad (10.65) \quad v=0 \rightarrow (11.85) \end{aligned}$$

\mathbf{a} : x 軸方向加速度

$$(11.88) \quad \mathbf{u} = c\hat{\mathbf{R}} \quad |\mathbf{u}| = c \quad u_x = c \frac{l}{R}$$

$$\begin{aligned} (11.89) \quad E_{lx} &= \frac{q/2}{4\pi\epsilon_0} \frac{R}{(cR)^3} [(c^2 + (l\hat{x} + d\hat{y}) \cdot \mathbf{a})u_x - (cR)a] \\ &= \frac{q/2}{4\pi\epsilon_0} \frac{R}{(cR)^3} [(c^2 + la)c \frac{l}{R} - (cR)a] \\ &= \frac{q/2}{4\pi\epsilon_0} \frac{1}{c^2 R^3} [(c^2 + la)l - (R^2)a] \\ &= \frac{q/2}{4\pi\epsilon_0} \frac{1}{c^2 (l^2 + d^2)^{3/2}} [(c^2 + la)l - (l^2 + d^2)a] \\ &= \frac{q}{8\pi\epsilon_0 c^2} \frac{lc^2 - ad^2}{(l^2 + d^2)^{3/2}} \end{aligned}$$

$$\dot{x}(t_r) = 0 \quad \text{instantaneously at rest} \rightarrow (11.91)$$

$$d = \sqrt{(cT)^2 - l^2} = \sqrt{(cT)^2 - \left(\frac{1}{2}aT^2 + \frac{1}{6}\dot{a}T^3 + \dots\right)^2} = cT \sqrt{1 - \left(\frac{1}{2c}aT + \frac{1}{6c}\dot{a}T^2 + \dots\right)^2}$$

$$\begin{aligned} (11.94) \quad l &= \frac{1}{2}aT^2 + \frac{1}{6}\dot{a}T^3 + \dots = \frac{1}{2}a \left(\frac{1}{c}d + \frac{a^2}{8c^5}d^3 + ()d^4 + \dots \right)^2 + \frac{1}{6}\dot{a} \left(\frac{1}{c}d + \frac{a^2}{8c^5}d^3 + ()d^4 + \dots \right)^3 + \dots \\ &= \frac{1}{2}a \left(\frac{1}{c^2}d^2 + 2\frac{1}{c}d \frac{a^2}{8c^5}d^3 + \dots \right) + \frac{1}{6}\dot{a} \left(\frac{1}{c^3}d^3 + 3\left(\frac{1}{c}d\right)^2 \frac{a^2}{8c^5}d^3 + \dots \right) + \dots \\ &= \frac{1}{2}a \left(\frac{1}{c^2}d^2 \right) + \frac{1}{6}\dot{a} \left(\frac{1}{c^3}d^3 \right) + ()d^4 + \dots \end{aligned}$$

$$(11.95) \quad lc^2 - ad^2 = -\frac{a}{2}d^2 + \frac{\dot{a}}{6c}d^3 + ()d^4 + \dots$$

$$l^2 + d^2 = \left(\frac{a^2}{4c^4}d^4 + \dots\right) + d^2 = d^2 + ()d^4 + \dots$$

$$\frac{lc^2 - ad^2}{(l^2 + d^2)^{3/2}} = \frac{-\frac{a}{2}d^2 + \frac{\dot{a}}{6c}d^3 + ()d^4 + \dots}{d^3} = -\frac{a}{2d} + \frac{\dot{a}}{6c} + ()d + \dots$$

$$\begin{aligned} (11.96) \quad \mathbf{F}_{\text{self}} &= \frac{q^2}{4\pi\epsilon_0} \left[-\frac{a(t_r)}{4c^2 d} + \frac{\dot{a}(t_r)}{12c^3} + ()d + \dots \right] \hat{\mathbf{x}} = \frac{q^2}{4\pi\epsilon_0} \left[-\frac{a(t) - \dot{a}(t)d/c}{4c^2 d} + \frac{\dot{a}(t)}{12c^3} + ()d + \dots \right] \hat{\mathbf{x}} \\ &= \frac{q^2}{4\pi\epsilon_0} \left[-\frac{a(t)}{4c^2 d} + \frac{\dot{a}(t)}{4c^3} + \frac{\dot{a}(t)}{12c^3} + ()d + \dots \right] \hat{\mathbf{x}} = \frac{q^2}{4\pi\epsilon_0} \left[-\frac{a(t)}{4c^2 d} + \frac{\dot{a}(t)}{3c^3} + ()d + \dots \right] \hat{\mathbf{x}} \end{aligned}$$

$$(11.97) \quad \mathbf{F}_{\text{self}} = 2m_0 a \quad \frac{q^2}{4\pi\epsilon_0} \left[-\frac{a(t)}{4c^2 d} + \frac{\dot{a}(t)}{3c^3} + ()d + \dots \right] = 2m_0 a$$

$$\left(2m_0 + \frac{q^2}{4\pi\epsilon_0} \frac{1}{4c^2 d} \right) a = \frac{q^2}{4\pi\epsilon_0} \left[\frac{\dot{a}(t)}{3c^3} + ()d + \dots \right] \quad m = 2m_0 + \frac{1}{4\pi\epsilon_0} \frac{q^2}{4dc^2} = 2m_0 + m' \quad \text{自己場の衣を着た質量}$$

$$E = \frac{1}{4\pi\epsilon_0} \frac{(q/2)^2}{d} = m'c^2$$

繰り込まれた質量

$$(11.80) \quad F_{\text{rad}} = \frac{\mu_0 q^2}{6\pi c} \dot{a} = \tau m \dot{a} = \tau \dot{F} \quad \tau = 6 \times 10^{-24} \text{ s} \quad \text{for electron} \quad (11.82)$$

$$a = a_0 \sin \omega t \quad \dot{a} = \omega a_0 \cos \omega t$$

$$F_{\text{rad}} = \tau \omega m a_0 \cos \omega t \quad \omega = 2\pi f \ll \frac{1}{\tau} \quad f \ll \frac{1}{2\pi\tau} = 3 \times 10^{22} \text{ Hz}$$

加速度の変化率が 3×10^{22} Hz より十分小さければ F_{rad} は無視できる